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This book teaches the fundamentals of CNC machining. Topics include safety, CNC tools, cutting speeds and feeds, coordinate systems, G-codes, 2D, 3D and Turning toolpaths and CNC setups and operation. Emphasis is on using best practices as related to modern CNC and CAD/CAM. This book is particularly well-suited to persons using CNC that do not have a traditional machining background.

Lonely because he is the only mouse in the church, Arthur asks all the town mice to join him. Unfortunately the congregation aren't so welcoming. But all is not lost when a robber tries to steal the church candlesticks, the



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mice foil his plans and win back their home.

Written by two of Europe's leading robotics experts, this book provides the tools for a unified approach to the modelling of robotic manipulators, whatever their mechanical structure. No other publication covers the three fundamental issues of robotics: modelling, identification and control. It covers the development of various mathematical models required for the control and simulation of robots. · World class authority · Unique range of coverage not available in any other book · Provides a complete course on robotic control at an undergraduate and graduate level

Presented here are 97 refereed papers given at the 37th MATADOR Conference held at The University of Manchester in July 2012. The MATADOR series of conferences covers the topics of Manufacturing Automation and Systems Technology, Applications, Design, Organisation and Management, and Research. The Proceedings of this Conference contain original papers contributed by researchers from many countries on different continents. The papers cover the principles, techniques and applications in aerospace, automotive, biomedical, energy, consumable goods and process industries. The papers in this volume reflect: the importance of manufacturing to international wealth creation; the emerging fields of micro- and nano-manufacture; the

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increasing trend towards the fabrication of parts using lasers; the growing demand for precision engineering and part inspection techniques, and the changing trends in manufacturing within a global environment.

Industrial communications are a multidimensional, occasionally confusing, mixture of fieldbuses, software packages, and media. The intent of this book is to make it all accessible. When industrial controls communication is understood and then installed with forethought and care, network operation can be both beneficial and painless. To that end, the book is designed to speak to you, whether you're a beginner or interested newbie, the authors guide you through the bus route to communication success. However, this is not a how-to manual. Rather, think of it as a primer laying the groundwork for controls communication design, providing information for the curious to explore and motivation for the dedicated to go further.

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The author has maintained two open-source MATLAB Toolboxes for more than 10 years: one for robotics and one for vision. The key strength of the Toolboxes provide a set of tools that allow the user to work with real problems, not trivial examples. For the student the book makes the algorithms accessible, the Toolbox code can be read to gain understanding, and the examples illustrate how it can be used—instant gratification in just a couple of lines of MATLAB code. The code can also be the starting point for new work, for researchers or students, by writing programs based on

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Toolbox functions, or modifying the Toolbox code itself. The purpose of this book is to expand on the tutorial material provided with the toolboxes, add many more examples, and to weave this into a narrative that covers robotics and computer vision separately and together. The author shows how complex problems can be decomposed and solved using just a few simple lines of code, and hopefully to inspire up and coming researchers. The topics covered are guided by the real problems observed over many years as a practitioner of both robotics and computer vision. It is written in a light but informative style, it is easy to read and absorb, and includes a lot of Matlab examples and figures. The book is a real walk through the fundamentals of robot kinematics, dynamics and joint level control, then camera models, image processing, feature extraction and epipolar geometry, and bring it all together in a visual servo system. Additional material is provided at <http://www.petercorke.com/RVC>

This book constitutes the refereed proceedings of the 4th International Conference on Simulation, Modeling, and Programming for Autonomous Robots, SIMPAR 2014, held in Bergamo, Italy, in October 2014. The 49 revised full papers presented were carefully reviewed and selected from 62 submissions. The papers are organized in topical sections on simulation, modeling,

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